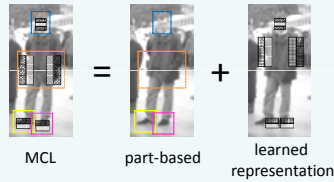


Multiple Component Learning for Object Detection

Piotr Dollár^{1,2} Boris Babenko² Pietro Perona¹ Serge Belongie^{1,2} Zhuowen Tu³
¹ Electrical Engineering, California Institute of Technology
² Computer Science and Engineering, University of California, San Diego
³ Lab of Neuro Imaging, University of California, Los Angeles
 pdollar@caltech.edu {bbabenko, sjb}@cs.ucsd.edu Zhuowen.tu@loni.ucla.edu

Goals

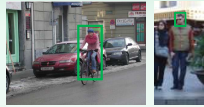
- Learn part-based classifier with weak supervision (object labels provided, but no part labels)
- Part models are classifiers from rich hypothesis class (rather than Gaussian distributions, templates, etc.)
- No complex inference since model is discriminative



Overview

(1) Learning a single part

- Weakly supervised learning
- Object location in positive images unknown
 - Developed for learning *objects*, use for *parts*
 - We use Multiple Instance Learning (MIL)



(2) Learning diverse parts

- What prevents learning same part repeatedly?
- Different *weighting* of data
 - Not all parts expressed in all images

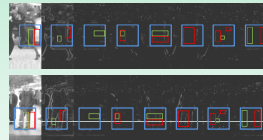


(3) Combining part detectors

- Boosting offers way of combining multiple diverse classifiers
- Train one weak (part) classifier using MIL
 - Re-weight samples according to current error
 - Repeat until training error sufficiently low

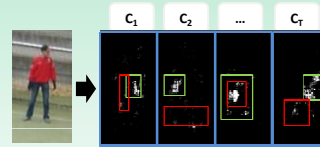
Pedestrian Detection

Low-level features



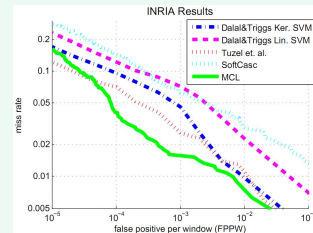
- Features for component classifiers
- Haars over multiple channels: gray (1), grad (1), quantized grad (6)

Incorporating Spatial Relations



- Features for overall classifier
- Densely compute component responses C_i
- Final classifier retrained with Haars over C_i

Results on INRIA Data

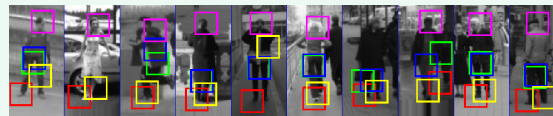


We achieve state of the art results.



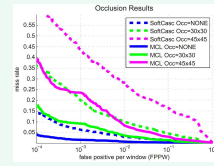
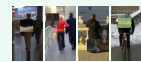
Single Scale Detection Results

Learned components (first 5)



Robustness to Occlusion

Artificial 30x30 occ:

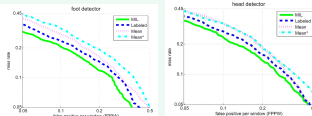


Artificial 45x45 occ:



MCL degrades gracefully w occ.

Role of Alignment



- Aligned data \rightarrow higher performance
- Can't simultaneously align articulated object without part based model

Multiple Component Learning (MCL)

Derivation

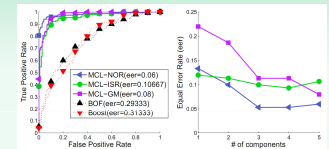
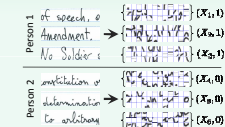
- Boosting
- Input: N training examples $\{x_i, y_i\}$ with $x_i \in \mathcal{X}$ and $y_i \in \mathcal{Y}$
- Combines T weak classifiers $h_t(x)$ to learn strong classifier: $H(x) = \text{sign}(\sum_{t=1}^T \alpha_t h_t(x))$
- Excellent generalization and strong theoretical foundation
- No assumptions about input space
- Only requires weak classifiers for arbitrary \mathcal{X} : $h_t: \mathcal{X} \rightarrow \{-1, 1\}$
- For example, can use \mathcal{X}^m (sets) in place of \mathcal{X}

Algorithm

Given: N labeled training examples (X_i, y_i) with $y_i \in \{-1, 1\}$ and $X_i = \{x_{i1}, \dots, x_{im}\}$, and initial distr. of weights $D_1(i) = \frac{1}{N}$ over the examples.
 For $t = 1, \dots, T$:
 • Train a MIL classifier $\tilde{F}_t: \mathcal{X}^m \rightarrow [0, 1]$ using distribution D_t . Let $\tilde{F}_t'(X_i) = (2 \times 1 \{ \tilde{F}_t(X_i) > th \} - 1)$, where $th = .5$ or is chosen to minimize ϵ_t .
 • Calculate error of \tilde{F}_t' : $\epsilon_t = \sum_{i=1}^N D_t(i) 1_{y_i \neq \tilde{F}_t'(X_i)}$.
 • Set $\alpha_t = -\frac{1}{2} \log(\epsilon_t / (1 - \epsilon_t))$.
 • Set $D_{t+1}(i) = D_t(i) \exp(-\alpha_t y_i \tilde{F}_t'(X_i)) / Z_t$, where $Z_t = 2 \sqrt{\epsilon_t (1 - \epsilon_t)}$ is a normalization factor.
 Output the MCL classifier: $\mathcal{F}(X) = \text{sign}(\sum_{t=1}^T \alpha_t \tilde{F}_t'(X))$

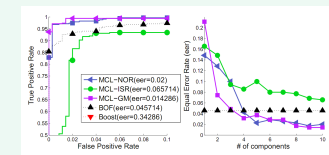
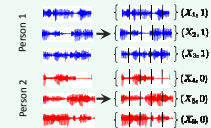
Other Applications

Writer Identification



- Text independent handwriting identification
- 2 people, 2 pages of text each
- Haar features on 25x25 patches

Speaker Identification



- Content independent speaker identification
- John Kerry vs. George W. Bush, 2004
- Standard MFCC features

Set Learning

	Standard	MIL	MCL
\mathcal{X}			
Training input	$\psi_i \in \mathcal{X}$	$X_i = \{x_{i1}, \dots, x_{im}\}$ $x_{ij} \in \mathcal{X}$	$X_i = \{x_{i1}, \dots, x_{im}\}$ $x_{ij} \in \mathcal{X}$
Goal	$f: \mathcal{X} \rightarrow \{0, 1\}$	$f: \mathcal{X} \rightarrow \{0, 1\}$	$\mathcal{F}: \mathcal{X}^m \rightarrow \{0, 1\}$

Summary

Advantages:

- General notion of parts (components)
- Component learning weakly supervised
- Principled, general algorithm
- State of the art results with simple features

Disadvantages:

- Large amount of data needed
- Evaluating all components slow (currently working on improving speed)